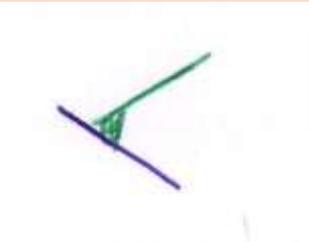
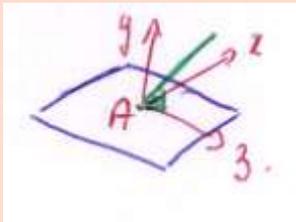
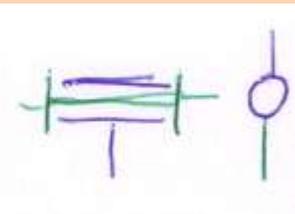
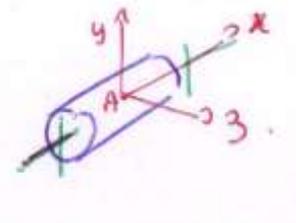
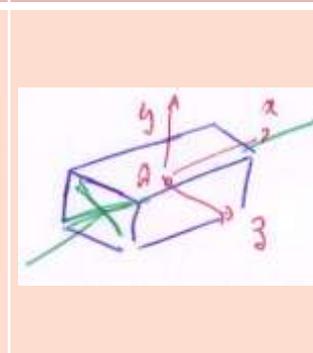
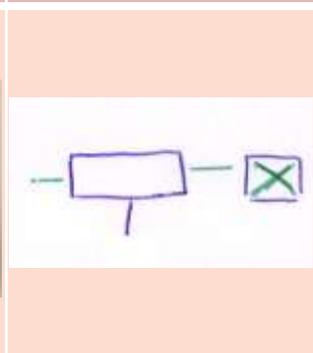


LIAISONS

Nom de la liaison	Photo	Représentation plane	Représentation spatiale avec repère local	Mobilité	Action mécanique transmissible												
Encastrement				<table border="1" data-bbox="1296 511 1590 758"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1615 525 1924 748"> <tr> <td>X_A</td> <td>L_A</td> </tr> <tr> <td>Y_A</td> <td>M_A</td> </tr> <tr> <td>Z_A</td> <td>N_A</td> </tr> </table>	X_A	L_A	Y_A	M_A	Z_A	N_A
T_x	R_x																
T_y	R_y																
T_z	R_z																
X_A	L_A																
Y_A	M_A																
Z_A	N_A																
Pivot				<table border="1" data-bbox="1296 886 1590 1080"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1615 858 1924 1052"> <tr> <td>X_A</td> <td>0</td> </tr> <tr> <td>Y_A</td> <td>M_A</td> </tr> <tr> <td>Z_A</td> <td>N_A</td> </tr> </table>	X_A	0	Y_A	M_A	Z_A	N_A
T_x	R_x																
T_y	R_y																
T_z	R_z																
X_A	0																
Y_A	M_A																
Z_A	N_A																

Nom de la liaison	Photo	Représentation plane	Représentation spatiale avec repère local	Mobilité	Action mécanique transmissible
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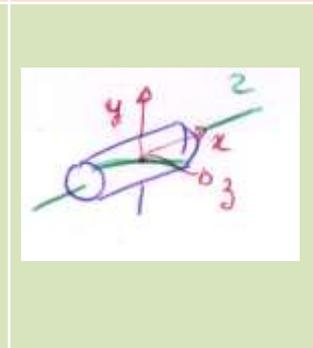
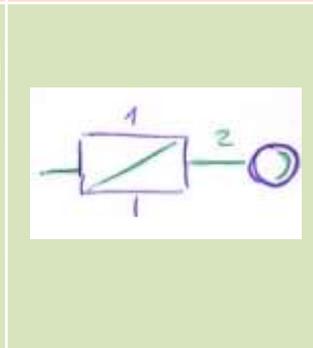
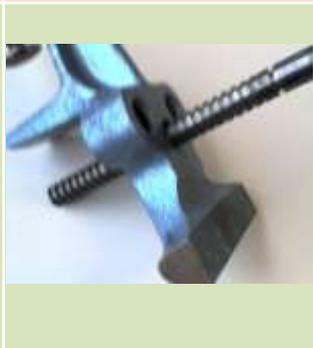
Glissière



T_x	R_x
I_y	R_y
I_z	R_z

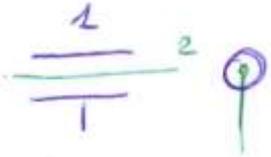
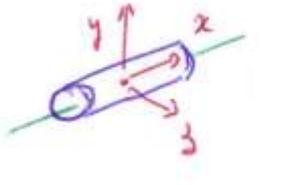
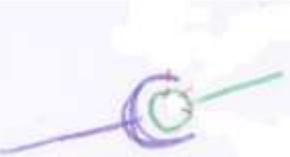
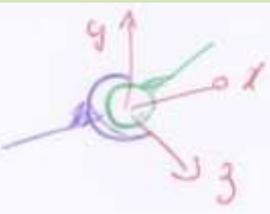
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Y_A	M_A
Z_A	N_A

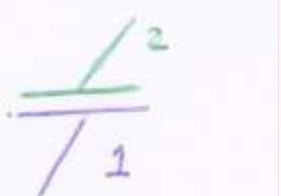
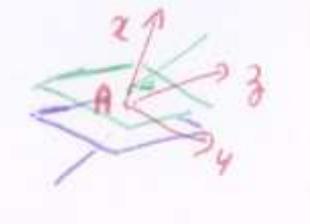
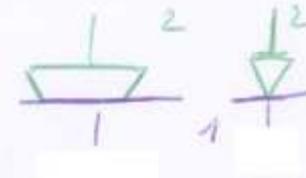
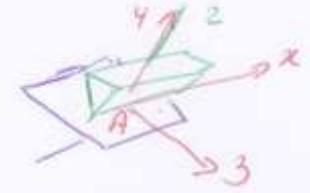
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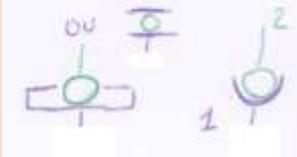
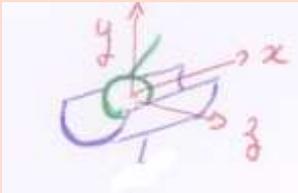
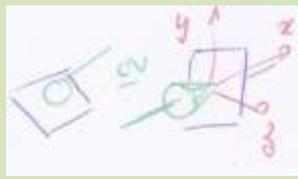
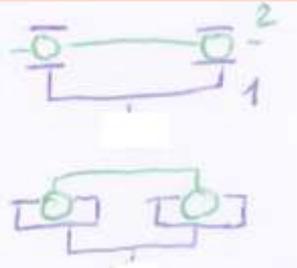
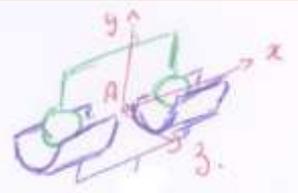


T_x	R_y
I_y	R_x
I_z	R_z

X_A	L_A
Y_A	M_A
Z_A	N_A

Nom de la liaison	Photo	Représentation plane	Représentation spatiale avec repère local	Mobilité	Action mécanique transmissible												
Pivot glissant				<table border="1" data-bbox="1302 534 1591 719"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1622 505 1912 705"> <tr> <td>0</td> <td>0</td> </tr> <tr> <td>Y_A</td> <td>M_A</td> </tr> <tr> <td>Z_A</td> <td>N_A</td> </tr> </table>	0	0	Y_A	M_A	Z_A	N_A
T_x	R_x																
T_y	R_y																
T_z	R_z																
0	0																
Y_A	M_A																
Z_A	N_A																
Rotule				<table border="1" data-bbox="1302 876 1591 1062"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1622 876 1912 1062"> <tr> <td>X_A</td> <td>0</td> </tr> <tr> <td>Y_A</td> <td>0</td> </tr> <tr> <td>Z_A</td> <td>0</td> </tr> </table>	X_A	0	Y_A	0	Z_A	0
T_x	R_x																
T_y	R_y																
T_z	R_z																
X_A	0																
Y_A	0																
Z_A	0																

Nom de la liaison	Photo	Représentation plane	Représentation spatiale avec repère local	Mobilité	Action mécanique transmissible												
Appui plan				<table border="1" data-bbox="1296 529 1599 715"> <tr> <td>I_x</td> <td>(R_x)</td> </tr> <tr> <td>(T_y)</td> <td>R_y</td> </tr> <tr> <td>(T_z)</td> <td>R_z</td> </tr> </table>	I_x	(R_x)	(T_y)	R_y	(T_z)	R_z	<table border="1" data-bbox="1619 529 1922 715"> <tr> <td>X_A</td> <td>0</td> </tr> <tr> <td>0</td> <td>M_A</td> </tr> <tr> <td>0</td> <td>N_A</td> </tr> </table>	X_A	0	0	M_A	0	N_A
I_x	(R_x)																
(T_y)	R_y																
(T_z)	R_z																
X_A	0																
0	M_A																
0	N_A																
Linéaire rectiligne				<table border="1" data-bbox="1296 865 1599 1043"> <tr> <td>(T_x)</td> <td>(R_x)</td> </tr> <tr> <td>T_y</td> <td>(R_y)</td> </tr> <tr> <td>(T_z)</td> <td>R_z</td> </tr> </table>	(T_x)	(R_x)	T_y	(R_y)	(T_z)	R_z	<table border="1" data-bbox="1619 865 1922 1043"> <tr> <td>0</td> <td>0</td> </tr> <tr> <td>Y_A</td> <td>0</td> </tr> <tr> <td>0</td> <td>M_A</td> </tr> </table>	0	0	Y_A	0	0	M_A
(T_x)	(R_x)																
T_y	(R_y)																
(T_z)	R_z																
0	0																
Y_A	0																
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Nom de la liaison	Photo	Représentation plane	Représentation spatiale avec repère local	Mobilité	Action mécanique transmissible												
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T_x	R_x																
T_y	R_y																
T_z	R_z																
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Y_A	0																
Z_A	0																
Ponctuelle				<table border="1" data-bbox="1294 782 1591 968"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1615 803 1932 993"> <tr> <td>X_A</td> <td>0</td> </tr> <tr> <td>0</td> <td>0</td> </tr> <tr> <td>0</td> <td>0</td> </tr> </table>	X_A	0	0	0	0	0
T_x	R_x																
T_y	R_y																
T_z	R_z																
X_A	0																
0	0																
0	0																
Deux LA en parallèle				<table border="1" data-bbox="1294 1153 1591 1339"> <tr> <td>T_x</td> <td>R_x</td> </tr> <tr> <td>T_y</td> <td>R_y</td> </tr> <tr> <td>T_z</td> <td>R_z</td> </tr> </table>	T_x	R_x	T_y	R_y	T_z	R_z	<table border="1" data-bbox="1615 1146 1932 1339"> <tr> <td>0</td> <td>0</td> </tr> <tr> <td>Y_A</td> <td>M_A</td> </tr> <tr> <td>Z_A</td> <td>N_A</td> </tr> </table>	0	0	Y_A	M_A	Z_A	N_A
T_x	R_x																
T_y	R_y																
T_z	R_z																
0	0																
Y_A	M_A																
Z_A	N_A																